

Quantum Gravity Phenomenology

A systematic approach

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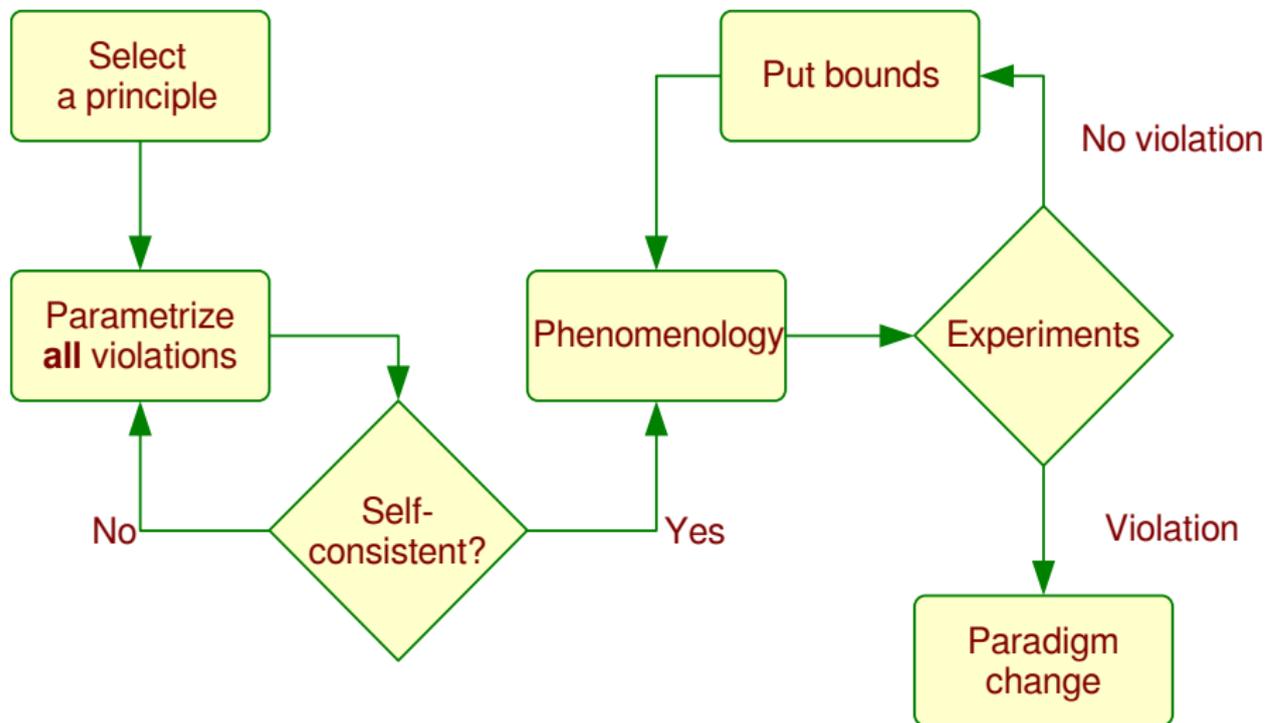
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Theoretical physics status

- Fundamental physics = GR + QM.
- Accurate empirical description (where we have access).
- Theoretically inconsistent \Rightarrow new theory (QG).
- Towards QG: top down vs. bottom up.
- No clues on the nature of QG!

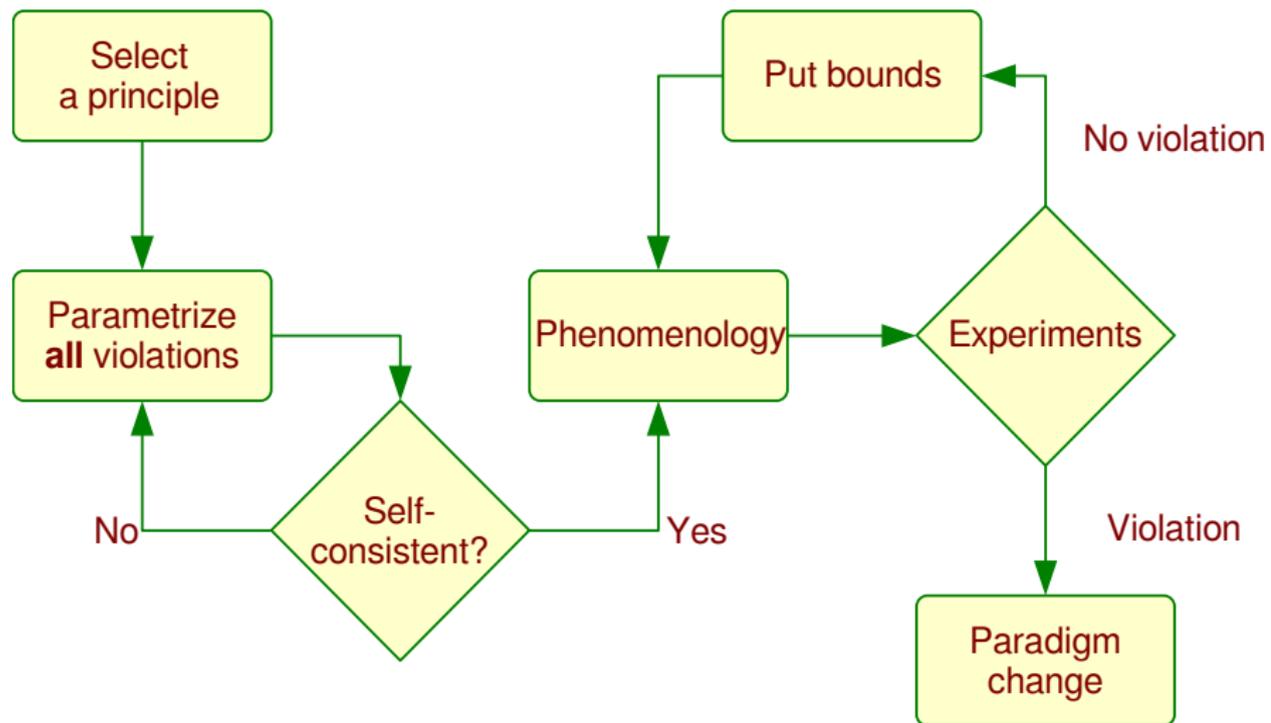


(Idealized) phenomenologists' workflow



- Often, steps 2 and 3 not considered.

Select a principle



GR principles

- Equivalence principle(s).
- Diffeomorphism invariance.
- Local Lorentz invariance.
- Einstein-Hilbert action.
- Torsion-free.
- 4 dims.
- \vdots



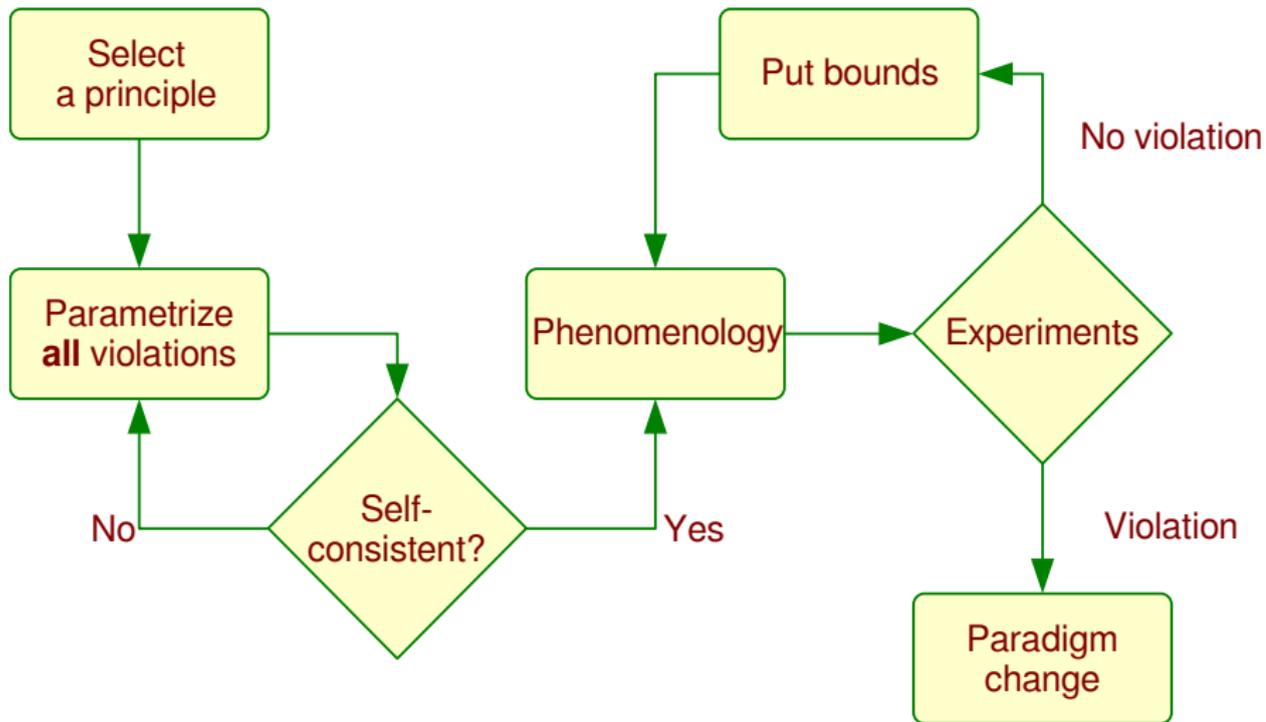
- These principles are not independent.
- In addition, we have the principles of quantum mechanics and the SM.

Lorentz invariance

- As an example, we focus on local Lorentz invariance.
- Lorentz invariance = *all* local inertial frames are equivalent.
- Inertial \leftrightarrow free particles (w.r.t. known interactions).
- No preferred (nondynamical) spacetime directions.
- At the level of the action: inv. under local $SO(1,3)$ “rotations” (tetrads).
- Motivation:
 - LI is fundamental for both GR and QFT.
 - LV includes CPT violation¹.
 - Motivated by spacetime discreteness.
 - Accommodated by most QG candidates (e.g., ST, LQG).
 - Possible discovery of new interactions.
 - Clear phenomenology: perform the same experiment in different frames.

¹Greenberg PRL 2002

Parametrize **all** violations



Effective field theory

- EFT is useful when the fundamental d.o.f. are unknown.
- Requires knowing the field content and symmetries.
- Field content = standard physics;
symmetries = standard physics without LI.
- Result: Most general parametrization!
Lagrange density¹

$$\mathcal{L} = \mathcal{L}_{\text{GR}} + \mathcal{L}_{\text{SM}} + \mathcal{L}_{\text{LV}}.$$

where \mathcal{L}_{LV} contains *all* possible LV additions to SM + GR.

- Naive expectation: \mathcal{L}_{LV} is suppressed by $E_{\text{EW}}/E_{\text{P}} \sim 10^{-17}$.
- Terms of every dimensionality (higher dimensions more suppressed).

¹“Standard Model Extension”: Colladay+Kostelecký PRD 1997; PRD 1998; Kostelecký PRD 2004;...

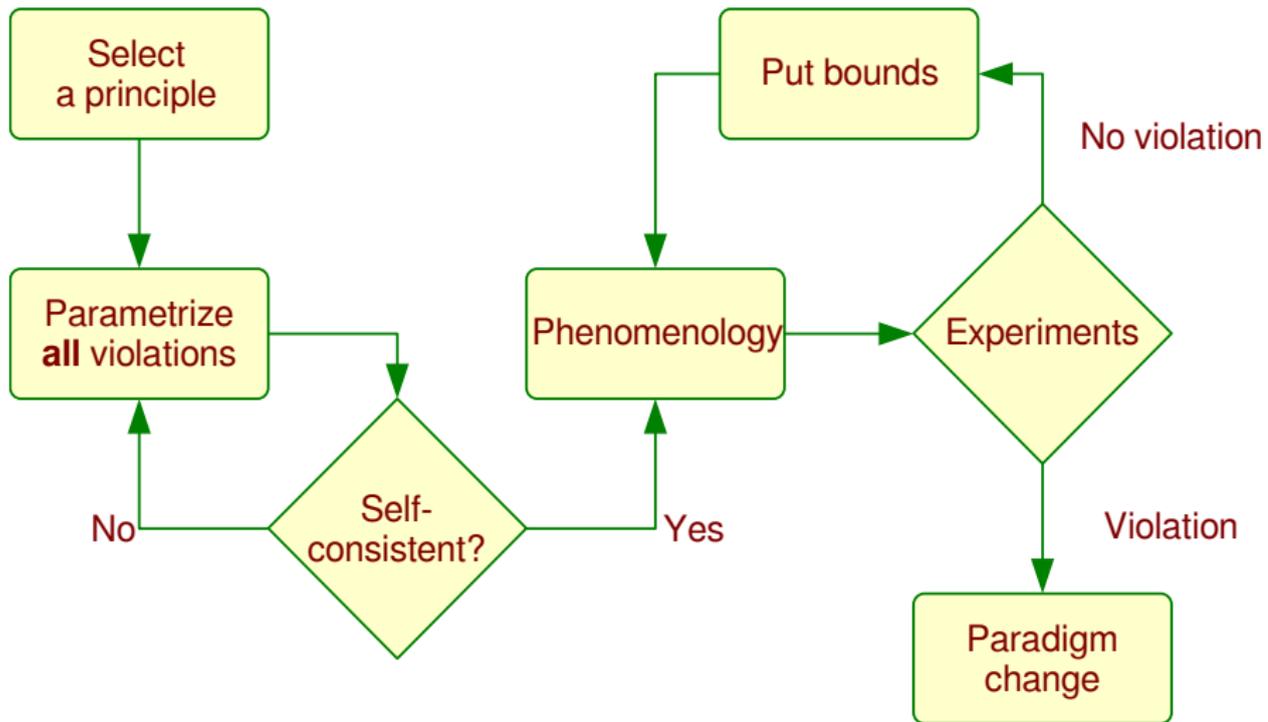
Example: Free Dirac spinor minimal sector in flat spacetime

- Minimal = operators of renormalizable dimension:

$$\begin{aligned}\mathcal{L} &= \frac{i}{2}\bar{\psi}\Gamma^\mu\partial_\mu\psi - \frac{i}{2}(\partial_\mu\bar{\psi})\Gamma^\mu\psi - \bar{\psi}M\psi, \\ \Gamma^\mu &= \gamma^\mu - \eta^{\mu\nu}c_{\rho\nu}\gamma^\rho - \eta^{\mu\nu}d_{\rho\nu}\gamma_5\gamma^\rho - \eta^{\mu\nu}e_\nu \\ &\quad - i\eta^{\mu\nu}f_\nu\gamma_5 - \frac{1}{2}\eta^{\mu\nu}g_{\rho\sigma\nu}\sigma^{\rho\sigma}, \\ M &= m + im_5\gamma_5 + a_\mu\gamma^\mu + b_\mu\gamma_5\gamma^\mu + \frac{1}{2}H_{\mu\nu}\sigma^{\mu\nu}.\end{aligned}$$

- Γ^μ and M are the most general matrices (e.g., m_5).
- SME coefficients: $a_\mu, b_\mu, c_{\mu\nu}, d_{\mu\nu}, e_\mu, f_\mu, g_{\mu\nu\rho}, H_{\mu\nu}$.

Phenomenology



Experiments and bounds

Experiments (partial list)

- Accelerator/collider.
- Astrophysical observations.
- Birefringence/dispersion.
- Clock-comparison.
- CMB polarization.
- Laboratory gravity tests.
- Matter interferometry.
- Neutrino oscillations.
- Particle vs. antiparticle.
- Resonant cavities and lasers.
- Sidereal/annual variations.
- Spin-polarized matter.

No evidence of LV \Rightarrow bounds:

“Data Tables for Lorentz and
CPT Violation”

Kostelecký+Russell RMP (2011),
(‘17 version:
arXiv:0801.0287v10)

- > 150 experimental results.
- Best bounds:
matter $\sim 10^{-34}$ GeV,
photons $\sim 10^{-43}$ GeV

Gravity SME sector

- Gravity is coupled with SME coefficients (not matter).
- “Minimal” subsector:

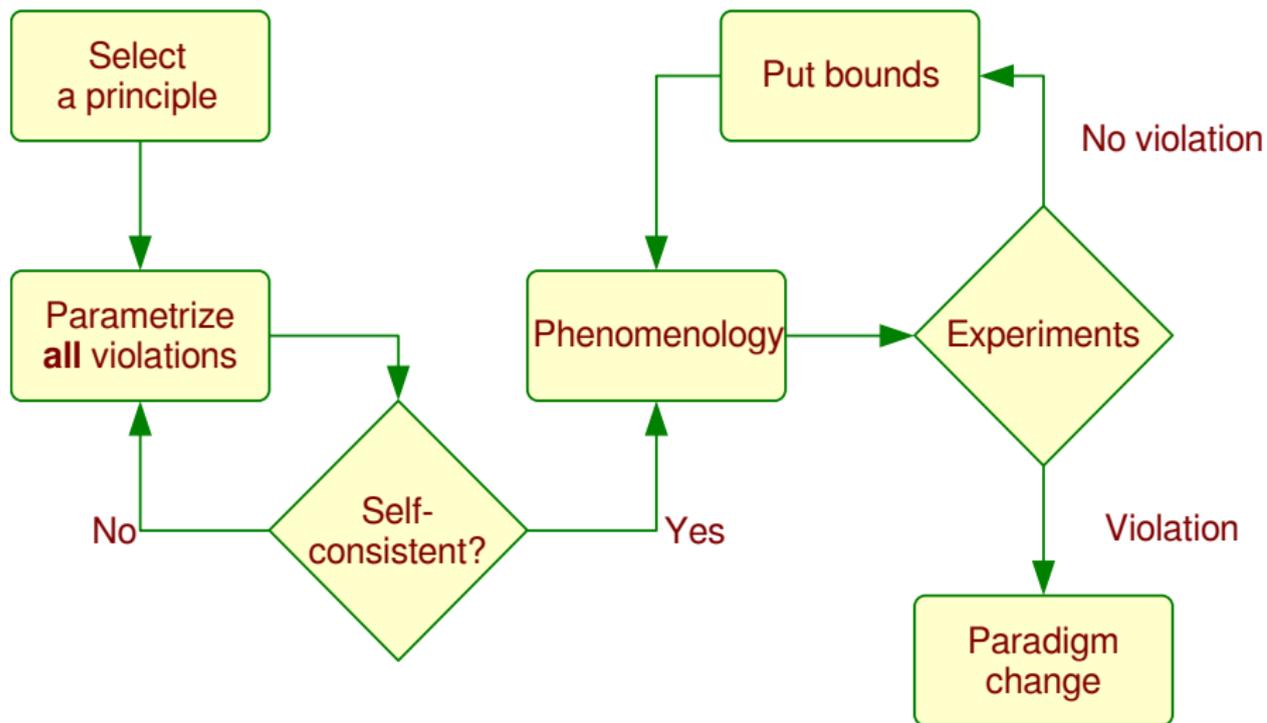
$$\begin{aligned}\mathcal{L}_{LV} &= \sqrt{-g} k^{abcd} R_{abcd} \\ &= \sqrt{-g} \left[-uR + s^{ab} R_{ab} + t^{abcd} W_{abcd} \right].\end{aligned}$$

- Decade long puzzle¹: “the t -puzzle.”
- Recently² found that t^{abcd} is indeed physical.
- Produces cosm. anisotropies during inflation (tensor modes).
- CMB data (BB angular power spectrum): $t^{0i0j} < 10^{-43}$.
- 29 orders of mag. improvement w.r.t. best bounds on s^{ab} !

¹Kostelecký+Bailey PRD 2006

²Bonder+León PRD 2017

Self-consistent?



Self-consistency

- Are there theoretical restrictions to rule out LV terms?
- In flat spacetime, few interesting tests.
 - Field redefinitions: Only some linear combinations of the coefficient's components are observable.
- Strong evidence that spacetime is not flat.
- Curved spacetime tests:
 - Field redefinitions.
 - Diffeomorphism invariance.
 - Dirac algorithm and Cauchy problem.
 - Gravitational d.o.f.
 - Spacetime boundaries.

Field redefinitions

- $\psi \rightarrow e^{i a_\mu x^\mu} \psi$ shows that $a_\mu \bar{\psi} \gamma^\mu \psi$ is unphysical.
- In flat spacetime, one-to-one correspondence between coordinates and vectors.
- This cannot be done in curved spacetime.
- Less field redefinitions \Rightarrow access more coefficients¹.
- No need for curvature, only nonminkowskian coordinates².
- The metric can be redefined \Rightarrow alternative constraints³.

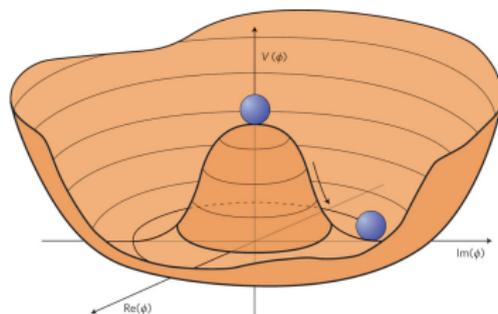
¹Kostelecký+Tasson PRD 2011

²Bonder PRD 2013

³Bonder PRD 2015

Diffeomorphism invariance

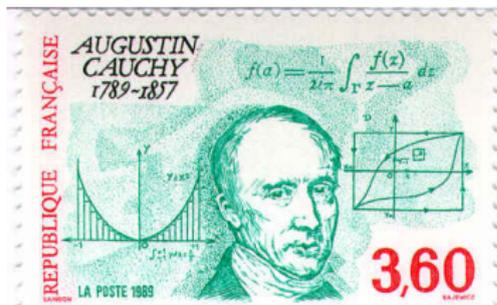
- Nondynamical fields break (active) diffeomorphism invariance.
- Thus, $\nabla_a T^{ab} \neq 0$, which goes against the Bianchi identities!
- Position: LV must be spontaneously broken¹.



¹Kostelecký PRD 2004

Dirac algorithm and Cauchy problem

- Dirac algorithm: Is there a Hamilton density for which the evolution respects the constraints?
- Cauchy problem:
 - Is the evolution uniquely determined by proper initial data?
 - Is the evolution continuous under changes of initial data.
 - Are the effects of modifying the initial data in agreement with spacetime causal structure?



- These conditions are difficult to verify without specifying the coefficients dynamics.

Cauchy problem: concrete model

- Focus on a concrete model¹:

$$\mathcal{L} = \frac{1}{2} D_\mu \phi D^\mu \phi^* - \frac{m^2}{2} \phi \phi^* - \frac{1}{4} B_{\mu\nu} B^{\mu\nu} - \frac{\kappa}{4} (B_\mu B^\mu - b^2)^2$$

- Flat spacetime, complex scalar field ϕ (matter), real vector field B^μ .
 - $B_{\mu\nu} = \partial_\mu B_\nu - \partial_\nu B_\mu$ and $D_\mu \phi = \partial_\mu \phi - ie B_\mu \phi$
 $\Rightarrow \mathcal{L}_{LV} = -B^\mu J_\mu$ and no gauge freedom.
 - Generalization of the Mexican hat potential, its VEV is timelike.
 - e , κ , and b are real positive constants.
- Canonical momenta:

$$\pi^0 = \frac{\delta \mathcal{L}}{\delta \partial_0 B_0} = 0, \quad \pi^i = \frac{\delta \mathcal{L}}{\delta \partial_0 B_i} = B^{i0},$$
$$p = \frac{\delta \mathcal{L}}{\delta \partial_0 \phi} = \frac{1}{2} (\partial_0 \phi^* + ie B_0 \phi^*) = (p^*)^*.$$

¹Bonder+Escobar PRD 2016

Cauchy problem: concrete model

$$\mathcal{L} = \frac{1}{2} D_\mu \phi D^\mu \phi^* - \frac{m^2}{2} \phi \phi^* - \frac{1}{4} B_{\mu\nu} B^{\mu\nu} - \frac{\kappa}{4} (B_\mu B^\mu - b^2)^2$$

- Two second-class constraints:

$$\chi_1 = \pi^0,$$

$$\chi_2 = \partial_i \pi^i - \kappa B_0 (B_\mu B^\mu - b^2) + 2e \text{Im}(\phi p).$$

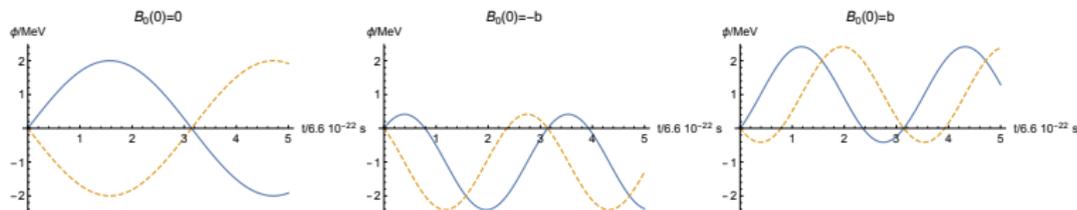
- The Dirac algorithm exhausted without inconsistencies.
- E.o.m. not of the form where one can use the “initial value” theorems.
- D.o.f.: B_i , π^i , ϕ , and p (only this initial data needed)
 \Rightarrow the initial B_0 obtained through the constraints.
- No unique initial $B_0 \Rightarrow$ ill-posed Cauchy problem!

Cauchy problem: concrete model

- Example (homogeneous): initially $B_i = 0$, $\pi^i = 0$, $\phi = 0$, and $p = a \in \mathbb{C}$.

$$\chi_2 = [B_0(0)^2 - b^2] B_0(0) = 0 \quad \Rightarrow \quad B_0(0) = b, 0, -b.$$

- Numerically ($\kappa = b/\text{MeV}^2 = e = m/\text{MeV} = \text{Re}(a)/\text{MeV} = \text{Im}(a)/\text{MeV} = 1$):



where the blue (yellow-dotted) line is for $\text{Re}\phi$ ($\text{Im}\phi$).

- ϕ represents matter \Rightarrow physical consequences!

Cauchy problem: concrete model

- Easy fix: change the kinetic term for $B_{\mu\dots}$ but the Cauchy problem for gravity can be damaged.
- Alternatives:
 - “Only one measurement” per spatial point (unlike a fundamental constant).
 - Consider B_0 as a standard d.o.f. (*i.e.*, naive application of Lagrange’s formalism \Rightarrow inequivalent quantizations?, discrete number of d.o.f.).
 - Construct a criteria to choose a special B_0 (e.g., initial energy, but there are degeneracies).
- Longterm goal: study if we can rule out spontaneous LV.



Gravitational degrees of freedom

- Palatini vs. conventional
 - For the minimal gravitational LV, the standard and Palatini approaches are equivalent¹.
 - More general field redefinitions, no practical applications!
 - For nonminimal LV, these approaches are inequivalent.
- Boundaries
 - In the phenomenological applications of LV, spacetime is conformally flat, which has boundaries.
 - For the minimal gravitational action, add²

$$\Delta S_{\text{LV}} = \pm 2 \int_{\text{boundary}} d^3x \sqrt{|h|} n_\mu n_\sigma k^{\mu\nu\rho\sigma} K_{\nu\rho}.$$

- Tricky to find ΔS_{LV} for the nonminimal part!

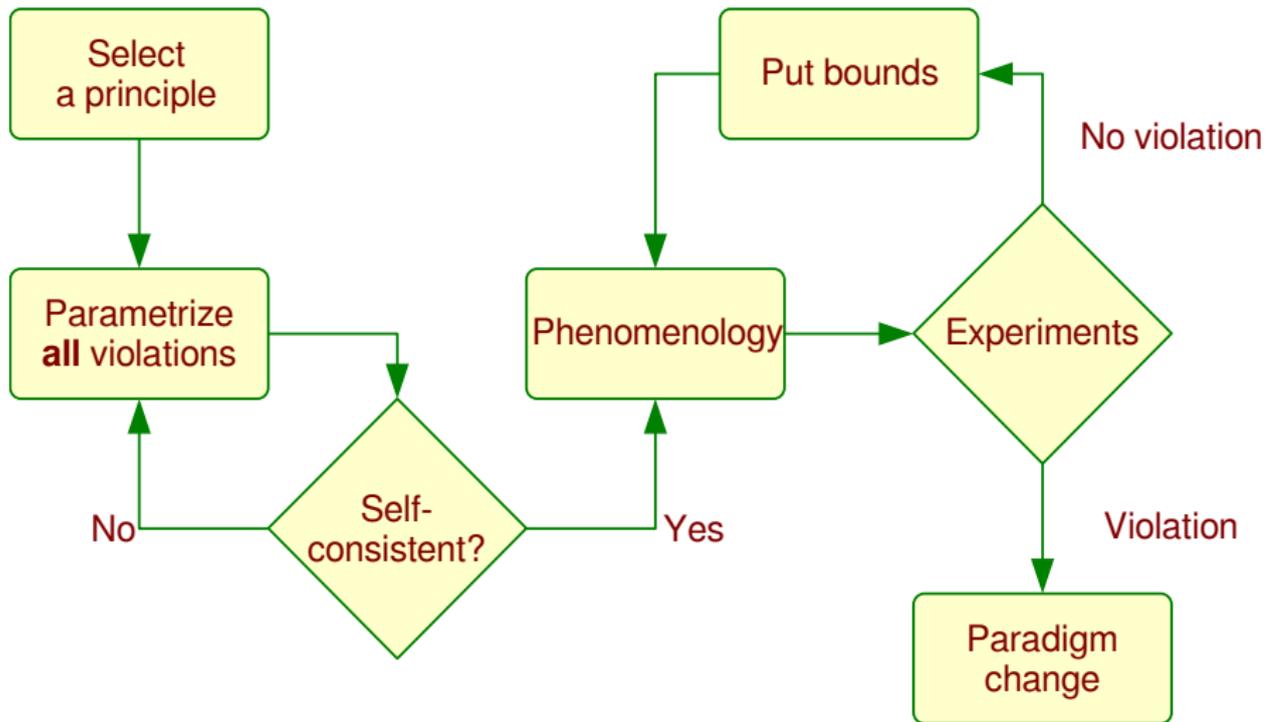
¹Bonder PRD 2015

²Bonder PRD 2015

Conclusions

- Looking for empirical clues of new physics could play an important role towards QG.
- This must be done systematically: with generality and checking the self-consistency.
- This type of program has been applied mainly for LV.
- EFT provides the general parametrization.
- Such a parametrization allows us to test LV experimentally and theoretically.
- New interesting phenomenological connections with cosmological observations.
- Several theoretical restrictions, mainly in curved spacetime.

Paradigm change



Gibbons-Hawking term

- In the minimal gravitational LV action-variation:

$$\begin{aligned} \delta S &\supset \frac{1}{2\kappa} \int_M d^4x \sqrt{-g} (g^{ca} \delta_d^b + k^{abcd}) \delta R_{abc}{}^d \\ &= \frac{1}{\kappa} \int_M d^4x \sqrt{-g} (\nabla_c \nabla_d k^{cabd}) \delta g_{ab} \\ &\quad + \frac{1}{\kappa} \int_{\partial M} d^3x \sqrt{|h|} n_c (2g^{a[c} g^{b]d} + k^{cabd}) \nabla_d \delta g_{ab} \end{aligned}$$

- In ∂M : $\delta g_{ab} = 0$ (and $\delta h_{ab} = \delta n^a = 0$) but $n^c \nabla_c \delta g_{ab} \neq 0$.
- $K_{ab} = h_a^c \nabla_c n_b \Rightarrow \delta K_{ab} = -h_a^c n_d \delta C_{cb}{}^d = \frac{1}{2} h_a^c n^d \nabla_d \delta g_{bc} \Rightarrow$
 $n_c (2g^{a[c} g^{b]d} + k^{cabd}) \nabla_d \delta g_{ab} = -\delta [(2h^{ab} \pm 2n_c n_d k^{cabd}) K_{ab}]$,
- To cancel the problematic term:

$$\Delta S = \frac{1}{\kappa} \int_{\partial M} d^3x \sqrt{|h|} (2h^{bc} \pm 2n_a n_d k^{abcd}) K_{bc}.$$

Variation under diffeomorphisms

- Nongravitational LV: $S = \int d^4x \sqrt{-g} R + 2\kappa S_m(g, \phi; k)$.
- Under a diffeo. assoc. with any ξ^a (of compact sup.):

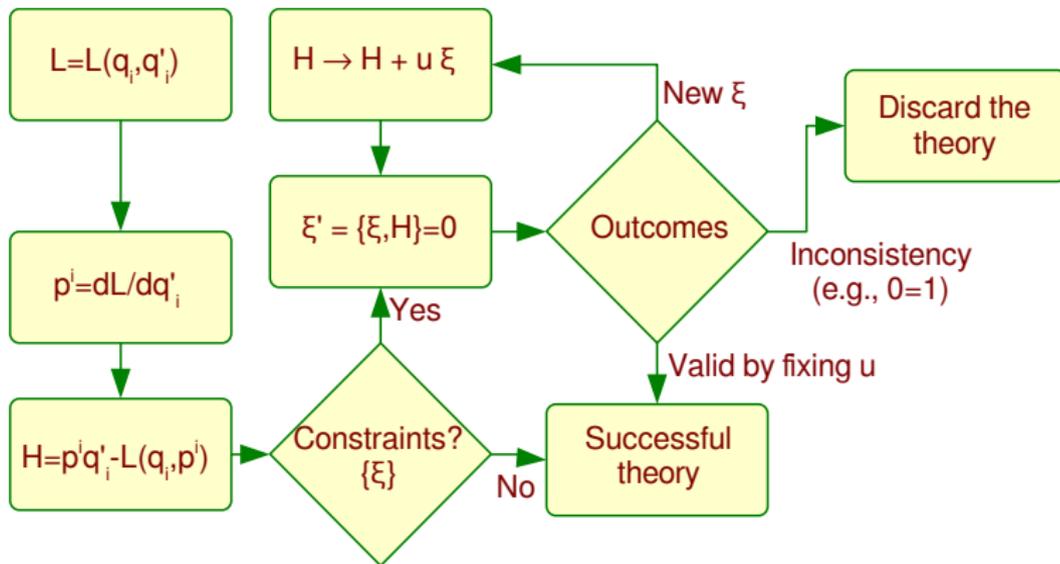
$$\begin{aligned}\delta S &= \int d^4x \left(\frac{\delta \sqrt{-g} R}{\delta g^{ab}} \delta g^{ab} + 2\kappa \frac{\delta \mathcal{L}_m}{\delta g^{ab}} \delta g^{ab} + 2\kappa \frac{\delta \mathcal{L}_{EH}}{\delta \phi} \delta \phi \right) \\ &= \int d^4x (-G_{ab} + \kappa T_{ab}) (-2\nabla^{(a} \xi^{b)}) \\ &= 2 \int d^4x (-\nabla^a G_{ab} + \kappa \nabla^a T_{ab}) \xi^b \\ &= 2\kappa \int d^4x \xi^b \nabla^a T_{ab},\end{aligned}$$

where we use that the fields ϕ satisfy their e.o.m., $\delta g^{ab} = \mathcal{L}_\xi g^{ab} = -2\nabla^{(a} \xi^{b)}$, and the Bianchi identity.

- Hence, $\delta S = 0$ if and only if $\nabla_a T^{ab} = 0$.

Dirac method

- Dirac's algorithm: method to construct *the* Hamiltonian.



- May reveal inconsistencies (example: $L(q, \dot{q}) = q$).

Cauchy theorems

- Cauchy-Kowalewski requires analytic initial data, which damages causality.

Theorem

(M, g_{ab}) globally hyperbolic, ∇_a any derivative operator. The following system of n linear equations for n unknown functions Ψ_1, \dots, Ψ_n

$$g^{ab}\nabla_a\nabla_b\Psi_i + A_{ij}^a\nabla_a\Psi_j + B_{ij}\Psi_j + C_i = 0,$$

where A_{ij}^a , B_{ij} , C_i are smooth vector/scalar fields, has a well-posed Cauchy problem.

- There are more general theorems¹.
- Most relevant: form of the second-derivative term.

¹Wald's GR book